MAIN FEATURES
- Laser scanners and software for welding robots
- Recognition, tracking and measuring in real time
- Various protocols for communication with robots

Laser Scanners RF627Weld Series. Working ranges

<table>
<thead>
<tr>
<th>Range</th>
<th>SMR, mm</th>
<th>MR, mm</th>
<th>XM, mm</th>
<th>XM, mm</th>
<th>Laser</th>
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<tr>
<td>65/25-21/25</td>
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<td>25</td>
<td>21</td>
<td>25</td>
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<tr>
<td>70/130-35/86</td>
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<td>130</td>
<td>35</td>
<td>86</td>
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<td>90/250-65/180</td>
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<td>250</td>
<td>65</td>
<td>180</td>
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</table>

For the rest parameters see “Overall specifications” in the previous page.

RF627Weld-65/25-21/25 and RF627Weld-90/250-65/180

RF627Weld-70/130-35/86

STEP 1
Connect equipment in accordance with functional diagram:
1. Connection between the scanner and Controller RIFTEK RF017 (or PC) with Riftek Lamia
2. Connection between Controller RIFTEK RF017 (or PC) with Riftek Lamia and the robot controller
3. Connection between the robot and the robot controller

STEP 2
Select Template

STEP 3
Select Robot Exchange Protocol

STEP 4
START WORKING

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