#### **PURPOSE**

Non-conact measuring and checking of surface profile, dimensions, deformations, flatness, gaps, volume, 3D models construction.

#### **WORKING PRINCIPLE**

Profiler operation is based on the principle of optical triangulation.

Radiation of a semiconductor laser is formed by a lens in a line and projected to an object. Radiation scattered from the object is collected by the lens and directed to a two-dimensional CMOS image sensor. The image of object outline thus formed is analyzed by a signal processor, which calculates the distance to the object (Z-coordinate) for each point of the set along the laser line on the object (X-coordinate). Profilers are characterized by base distance (beginning of the range), SMR, for Z-coordinate, measuring range (MR) for Z-coordinate, measuring range for X-coordinate at the beginning of Z (Xsmr) and measuring range for X-coordinate at the end of Z (Xemr).

#### **MODELS**

**RF627Smart** — profilers with in-built measurement functions and industry protocols

**RF627BiSmart** — dual-camera profilers with in-built measurement functions and industry protocols

RF628 — high speed profilers

**RF629** — high speed profilers with increased resolution

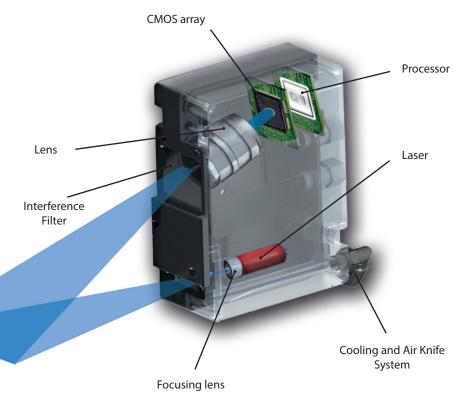
**RF6292** — high speed profilers with increased resolution and increased "laser line length/range" ratio

**RF627Smart-Weld** — profilers for welding robots with in-built functions of weld seam tracking and measurement

**RF627AVIKScan** — hand-held profilers for weld seam geometry control

#### **MAIN FEATURES**

- Measuring ranges from 10 to 1010 mm
- 0.01% linearity
- Sampling rate up to 16000 profiles/s
- Profilers with RED, BLUE and IR lasers
- Laser Safety Class 2M
- Dual camera profilers
- Trigger and encoder synchronization, mutual synchronization
- WEB-interface
- Free SDK and examples for Windows, Linux, .NET, MATLAB, LabVIEW
- Specialized profilers for hole control
- Profilers with air and water cooling
- Profilers with powerful lasers (1.2W red, 1.5W blue)
- Built-in standard industrial protocols and interfaces for robots













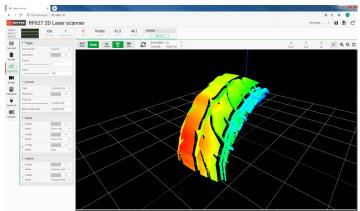


#### **SOFTWARE**

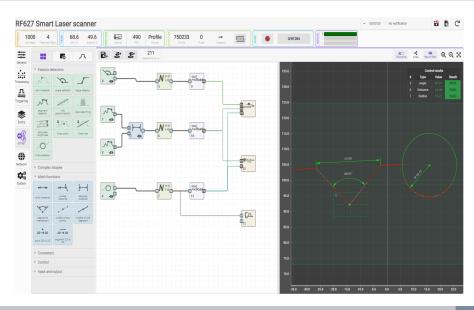
INTEGRATED WEB-INTERFACE for profilers parameterization, image and profile visualization

- Setting sensor parameters
- Data receiving, storage, visualization





#### **SMART-PROFILERS**



RF627Smart profilers makes it possible to measure geometric parameters of the object profile in real time directly in the profiler without connecting to a computer. Analysis, calculations, measurements, tolerance control are carried out according to the algorithm created by the user. To build the algorithm, a simple and intuitive tool is provided - a computation graph. The graph is formed from a library of ready-made blocks. Various combinations of blocks and connections between them allow the user to create an almost unlimited number of measuring functions, as well as to process profiles of any complexity. Measurement results can be transmitted via various protocols (Ethernet/IP, Modbus TCP, UDP), as well as to the logic outputs of the profiler in order to control the actuators and notify about product suitability.

#### RF62x Basic technical data

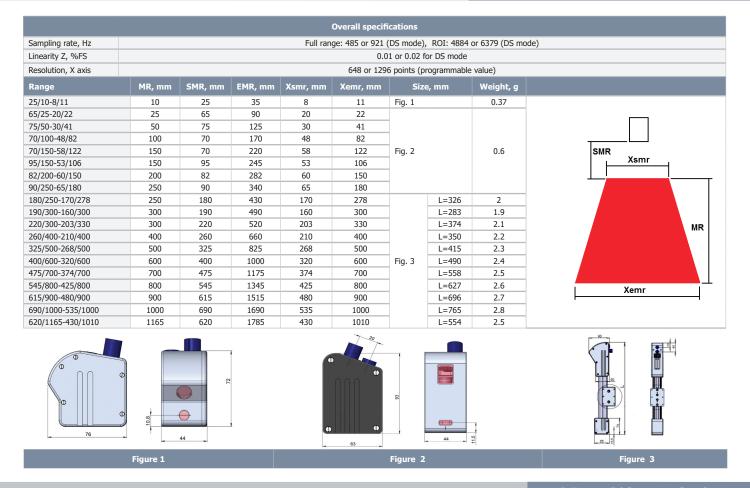


Laser		
Laser	660 nm or 405 nm or 450 nm 808 nm Class 2M по IEC/EN 60825-1:2014 or Class 3B on request	
Basic	Ethernet / 1000 Mbps	
Synchronization inputs	RS422, 3 channels	
Laser on/off hardware input	1	
Outputs	RS422, 1 channel	
Power supply	930 V or 1236 V for profilers with Blue laser	
Power consumption, not more	RF627Smart - 6 W (without a built-in heater) RF627BiSmart - 11 W, RF628 - 17 W RF629 µ RF6292 - 17 W	

Environment resistance				
Enclosure rating	IP67			
Vibration	20 g / 101000 Hz, 6 hours for each of XYZ axes			
Shock	30 g/6 ms			
Operating ambient temperature, °C	-20+40, or -40+40 for profilers with built-in heater, or -40+120 for profilers with built-in heater and cooling system			
Relative humidity	5-95% (no condensation)			
Storage temperature, °C	-20+70			
Housing/windows material	aluminum/glass			

#### **SMART PROFILERS**

### **RF627Smart Series**

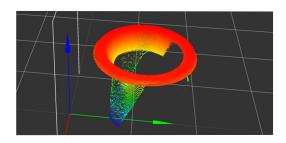


#### **DUAL CAMERA PROFILERS**

### **RF627BiSmart Series**

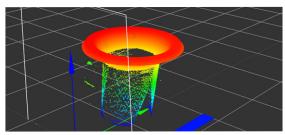
- Profilers with a single laser and two receiving cameras for high-quality 3D model generation
- Sampling rate (full working range) 520 profiles/s
- Resolution, X axis (combined profile) 1456 or 2912 points
- Full support for Smart functions

Range	MR, mm	SMR, mm	EMR, mm	Xsmr, mm	Xemr, mm
65/25-20/22	25	65	90	20	22
75/50-30/41	50	75	125	30	41
70/100-48/82	100	70	170	48	82
70/150-58/122	150	70	220	58	122
95/150-53/106	150	95	245	53	106
82/200-60/150	200	82	282	60	150
90/250-65/180	250	90	340	65	180



3D model of a conical hole, monocular profiler





3D model of a conical hole, binocular profiler

#### **HIGH SPEED PROFILERS**

### **RF628 Series**

- Sampling rate (full working range) > 4000 profiles/sec
- Sampling rate (ROI mode) up to 16000 profiles/sec
- Linearity, Z axis 0.01% of the range
- Resolution, X axis 640 or 1280 points

Range	MR, mm	SMR, mm	EMR, mm	Xsmr, mm	Xemr, mm
65/10-11/12	10	65	75	11	12
75/25-20/22	25	75	100	20	22
90/50-32/44	50	90	140	32	44
125/75-42/58	75	125	200	42	58
150/100-50/74	100	150	250	50	74
150/150-64/112	150	150	300	64	112
210/300-148/276	300	210	510	148	276
285/400-198/376	400	285	685	198	376
370/500-250/466	500	370	870	250	466
450/600-300/556	600	450	1000	300	556
530/700-350/650	700	530	1230	350	650
610/800-400/744	800	610	1410	400	744
685/900-450/836	900	685	1585	450	836
765/1000-500/930	1000	765	1765	500	930



#### HIGH SPEED PROFILERS WITH INCREASED RESOLUTION

### RF629, RF6292 Series



#### RF629

- Sampling rate (full working range) 1000 Hz
- Sampling rate (ROI mode) 16000 Hz
- Resolution, X axis 1280 or 2560 points
- Linearity, Z axis 0.01%

Range	MR, mm	SMR, mm	EMR, mm	Xsmr, mm	Xemr, mm
60/25-22/26	25	60	85	22	26
60/50-36/50	50	60	110	36	50
65/100-56/100	100	65	165	56	100
90/150-70/140	150	90	240	70	140
110/200-84/178	200	110	310	84	178
95/250-100/250	250	95	345	100	250
190/300-120/300	300	190	490	120	300
145/400-158/400	400	145	545	158	400
180/500-198/500	500	180	680	198	500
230/600-236/600	600	230	830	236	600
265/700-274/700	700	265	965	274	700
310/800-314/800	800	310	1110	314	800
345/900-352/900	900	345	1245	352	900
375/1000-392/1000	1000	375	1375	392	1000





#### RF6292

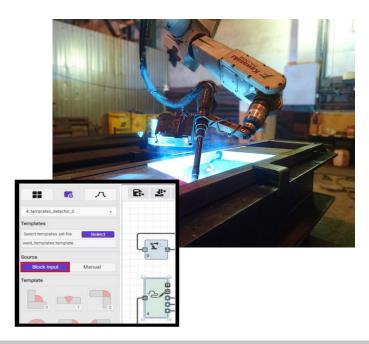
- Specialized profilers with Xend/Z ratio >2/5
- Sampling rate (full working range) > 4000 Hz
- Resolution, X axis 1280 or 2560 points
- Linearity, Z axis 0.01%

Range	MR, mm	SMR, mm	EMR, mm	Xsmr, mm	Xemr, mm
70/5-24/24	5	70	80	24	24
80/15-40/44	15	80	95	40	44
95/25-70/81	25	95	120	70	81
135/35-90/105	35	135	170	90	105
170/45-110/130	45	170	215	110	130
170/75-146/194	75	170	245	146	194
220/90-200/256	90	220	310	200	256
355/120-302/376	120	355	575	302	376
455/170-400/500	170	455	625	400	500
550/225-500/624	225	550	775	500	634

## LASER SEAM TRACKING SYSTEM FOR WELDING AUTOMATION

#### LASER PROFILERS FOR WELDING ROBOTS

### **RF627SMART-WELD SERIES**



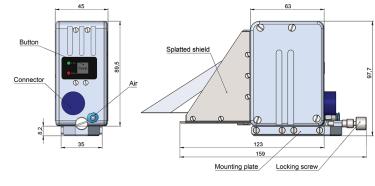
#### **MAIN FEATURES**

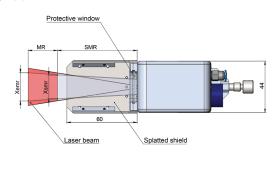
- RF627Smart-Weld laser profilers with direct connection to the robot controller
- Real-time recognition, tracking, and measurement
- Works with all surfaces, including shiny ones
- Connection to all common robot controllers

D	SMR,	MR,	Xsmr,	Xemr,	
Range	mm	mm	mm	mm	Laser
65/25-20/22	25	65	20	22	
70/50-30/41	50	70	30	41	Class 2M
76/100-48/82	100	76	48	82	
70/130-40/86	130	70	40	86	
250/130-52/76	130	250	52	76	
82/200-60/150	200	82	60	150	
90/250-65/180	250	90	65	180	

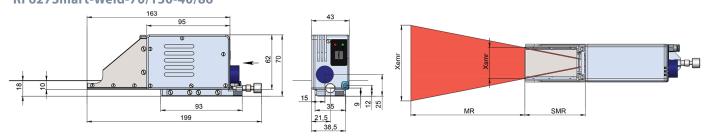
#### **RF627SMART-WELD**

#### RF627Smart-Weld-68/25-20/22 и RF627Smart-Weld-90/250-65/180





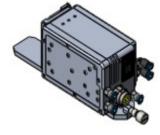
#### RF627Smart-Weld-70/130-40/86



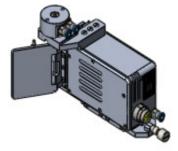
#### **RF627SMART-WELD CONFIGURATIONS**



Profiler for welding robot



Profiler for welding robot with cooling



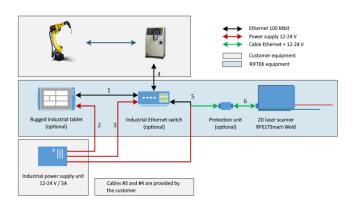
Profiler for welding robot with protective shutter

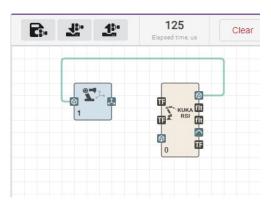
## LASER SEAM TRACKING SYSTEM FOR WELDING AUTOMATION

STEP 1 STEP 2

Connect the equipment according to the functional diagram:

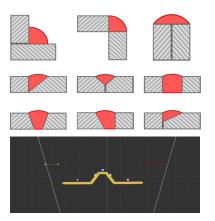
Calibrate the profiler relative to the robot.





STEP 3.1 STEP 3.2

Using the profiler web interface, create a computation graph from the library of ready-made blocks, taking into account the features of the equipment, namely:



Select a tracking template or create your own using the template editor.



Select a Smart-block of the robot communication protocol.

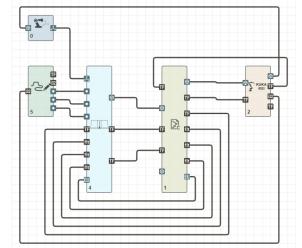


Select a Smart-block for the type of tracking:

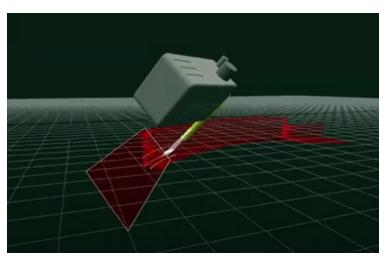
- 1. Output values of the smart block
- points and angles to which the actuator should move.
- 2. Output values of the smart-block
- linear and angular velocities with which the actuator should move.

STEP 3.3 STEP 4 START WORKING

HND1 protoco



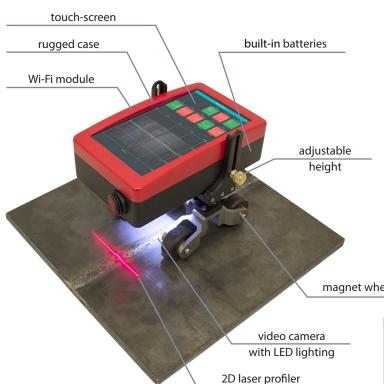
Add and configure the Smart block for script execution. Complete the construction of the tracking graph.



Observe the process on the computer screen.

#### SPECIALIZED SCANNING SYSTEMS FOR WELDS, WELDED JOINTS AND EDGE PREPARATION

RF627AVIKScan



- Integrated in one system:
  - 2D profiler for measurement control automation
  - video camera for visual control automation
- Sampling rate more than 2000 profiles/s
- Linear parameters measurement error ±0.05 mm for 100 mm range
- Defect detection (porosity, cracks)
- Real time OK/NOK analysis
- Systems mounted on the robot
- Interchangeable measuring heads with different ranges

magnet wheels with built-in encoder

Parameter	Value
2D profiler VOF, mm	Z - 120, X - 30110
Sampling frequency, profiles/s	>2000
Measurement error, mm	±0.05
X resolution, mm	0.0250.08
Color camera resolution	1296 x 976
Camera speed, frames/s	120
Laser	red (660 nm) or blue (405 нм), Class 2
Working temperature, °C	-4050
Measured parameters	width, height, angles, mismatch, undercut and so on

#### **EDGE PREPARATION CONTROL**





MEASUREMENT OF OFFSET, JOINT ANGLE, GAP WIDTH AND ETC.

#### WELD CONTROL





MEASUREMENT OF WELD HEIGHT AND WIDTH, CUTTING DEPTH, CAMBER AND ETC.

#### DESIGN

### 154 110 110 106 122 110 110 13,5

#### 3D VISUALIZATION SOFTWARE

